

Mapping Features to Automatically Identified Object-Oriented Variability Implementations

The case of ArgoUML-SPL

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Variability-Rich Systems with a Single Code Base



16.000 options managed
in 25M LoC [Acher2018]

#ifdef



ANDROID

24.000 different platforms in
2015 [Open2015]

Object-orientation

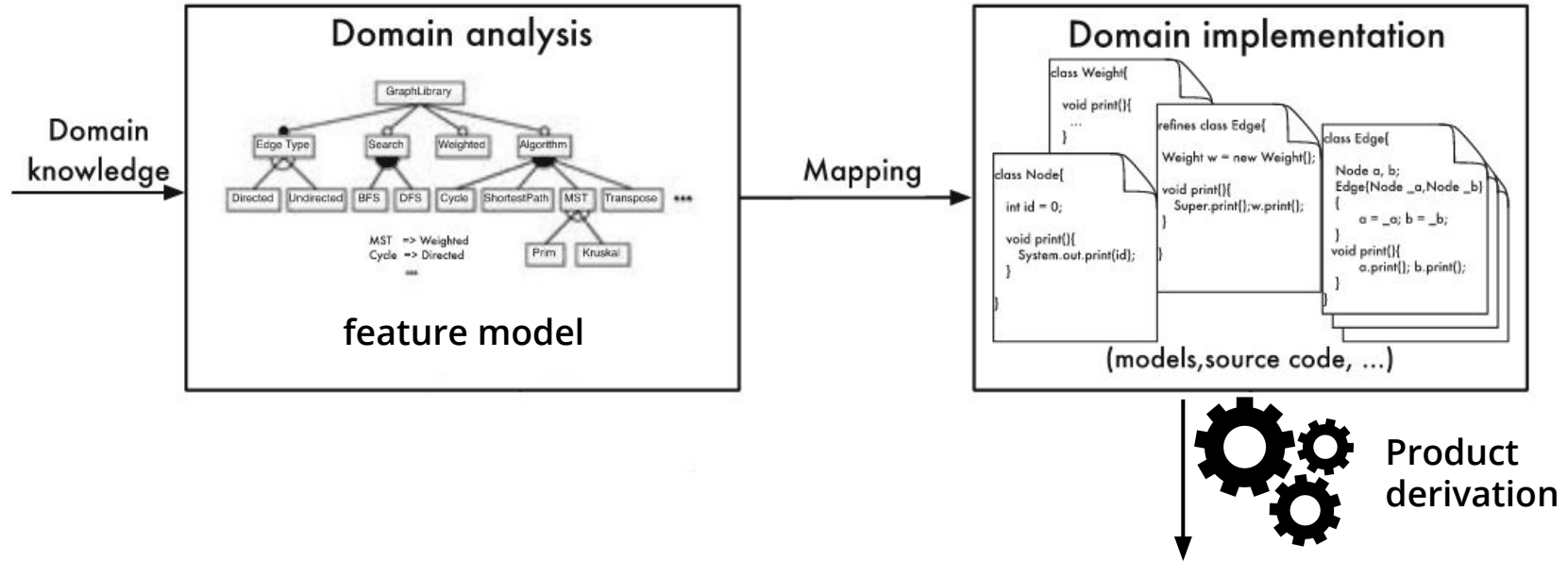


2.000+ options generating variants for
platforms, security levels... [Acher2018]

Object-orientation

and many variability implementation techniques...

Problem: How to master them as SPL?



How to engineer an SPL?

Forward-engineering:

Feature model → Domain implementation

Mapping between feature model and features is done **during the implementation**

How to engineer an SPL?

Forward-engineering:

Feature model → Domain implementation

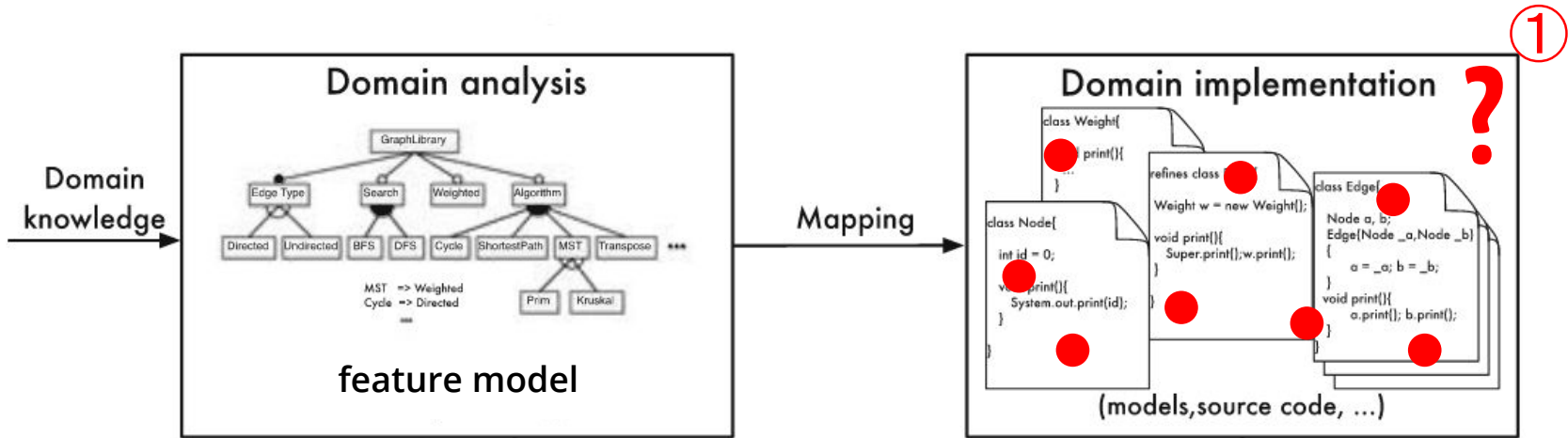
Mapping between feature model and features is done **during the implementation**

Reverse-engineering:

Feature model ← Domain implementation

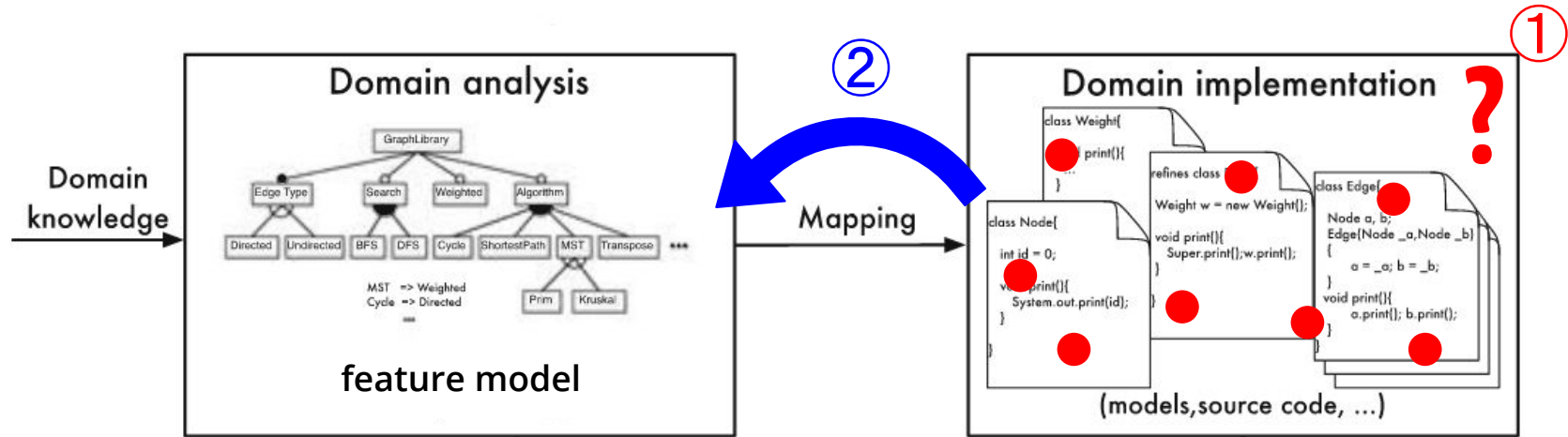
Need to extract the features and build a mapping with the feature model, or build it

Problem 1: How to identify variability implementations in an existing codebase?



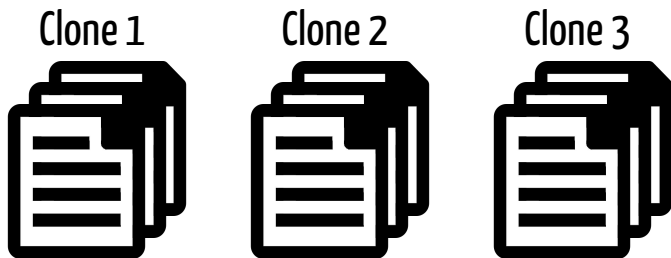
Problem 1: How to identify variability implementations in an existing codebase?

Problem 2: How to map these variability implementations to domain features?



State of the art on variability implementations detection

Context: [projects clones](#)

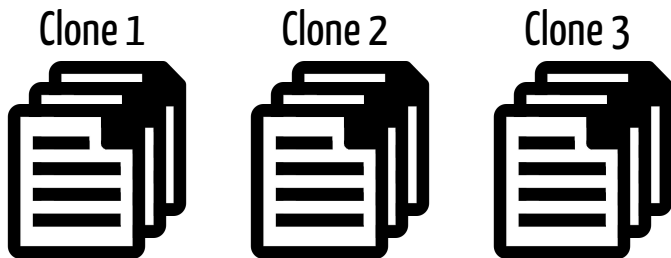


Detection method:

Comparison between clones and mapping with the domain features [Wesley2017]

State of the art on variability implementations detection

Context: [projects clones](#)

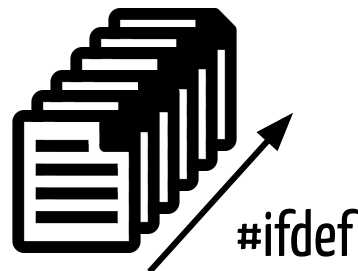


Detection method:

Comparison between clones and mapping with the domain features [Wesley2017]

Context: unique codebase and [preprocessing directives](#)

#ifdef → variant



Detection method:

Determining the consistency of directives [Liebig2010]

State of the art on variability implementations detection

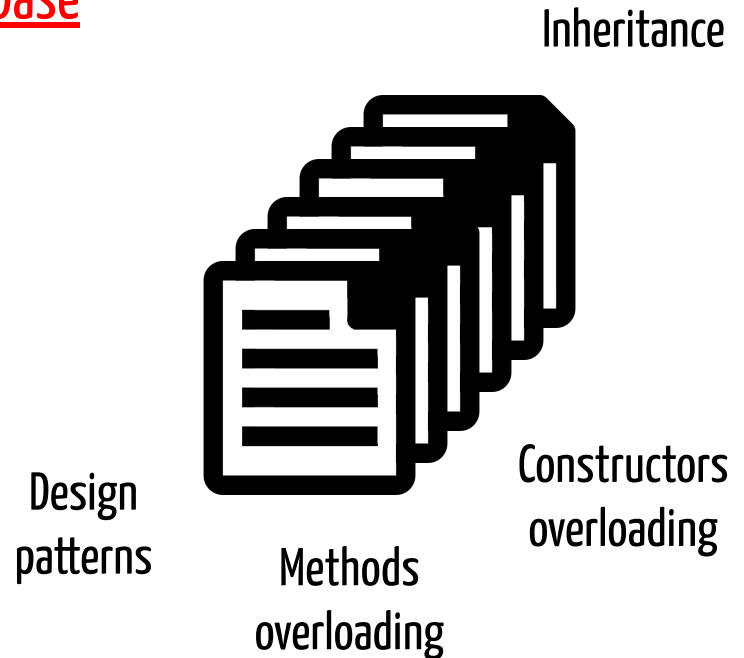
Our context: large and unique object-oriented codebase

- Several implementation mechanisms
- Variability buried in the code (variation points)

Detection method:

Currently no method

[Lozano2011], [Metzger2014], [Těrnava2017]



Variation points and variants

```
1 | public abstract class Shape {
2 |     public abstract double area();
3 |     public abstract double perimeter(); /*...*/
4 | }
5 |
6 | public class Circle extends Shape {
7 |     private final double radius;
8 |     // Constructor omitted
9 |     public double area() {
10 |         return Math.PI * Math.pow(radius, 2);
11 |     }
12 |     public double perimeter() {
13 |         return 2 * Math.PI * radius;
14 |     }
15 | }
```

```
15 | public class Rectangle extends Shape {
16 |     private final double width, length;
17 |     // Constructor omitted
18 |     public double area() {
19 |         return width * length;
20 |     }
21 |     public double perimeter() {
22 |         return 2 * (width + length);
23 |     }
24 |     public void draw(int x, int y) {
25 |         // rectangle at (x, y, width, length)
26 |     }
27 |     public void draw(Point p) {
28 |         // rectangle at (p.x, p.y, width, length)
29 |     }
30 | }
```

Variation points and variants

```
1 | public abstract class Shape {
2 |     public abstract double area();
3 |     public abstract double perimeter(); /*...*/
4 | }
```

vp_shape

```
5 | public class Circle extends Shape {
6 |     private final double radius;
7 |     // Constructor omitted
8 |     public double area() {
9 |         return Math.PI * Math.pow(radius, 2);
10 |    }
11 |    public double perimeter() {
12 |        return 2 * Math.PI * radius;
13 |    }
14 | }
```

v_circle

```
15 | public class Rectangle extends Shape {
16 |     private final double width, length;
17 |     // Constructor omitted
18 |     public double area() {
19 |         return width * length;
20 |     }
21 |     public double perimeter() {
22 |         return 2 * (width + length);
23 |     }
```

v_rectangle

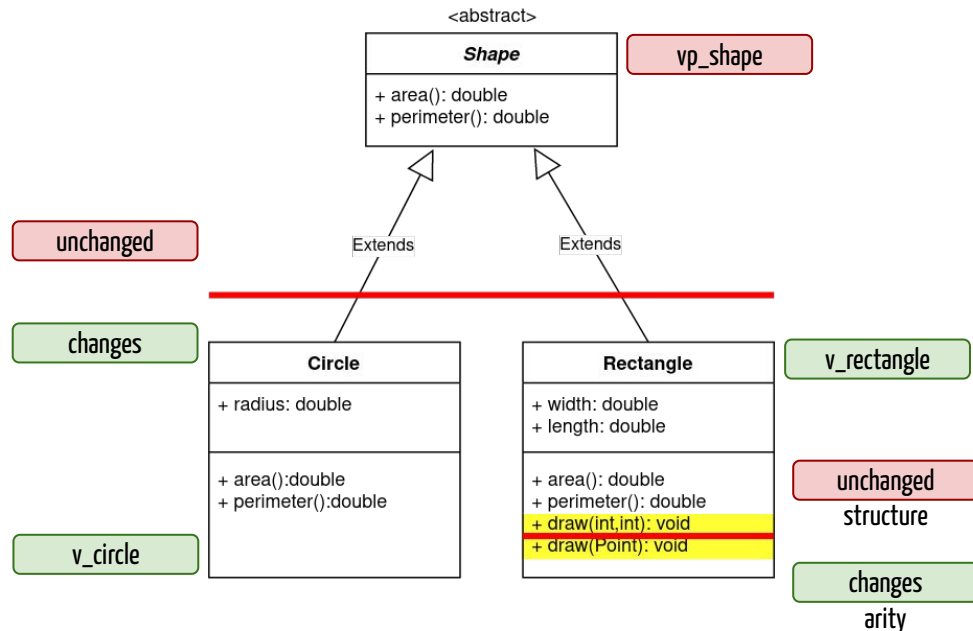
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24 | public void draw(int x, int y) {
25 |     // rectangle at (x, y, width, length)
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27 | public void draw(Point p) {
28 |     // rectangle at (p.x, p.y, width, length)
29 | }
30 | }
```

vp_draw

Use of symmetries to detect variability implementations?

Intuition:

- Presence of **symmetries in object-oriented codebases** [Coplien2019] inspired from the theory of centres [Alexander2002]
- Symmetries present in **mechanisms implementing variability**



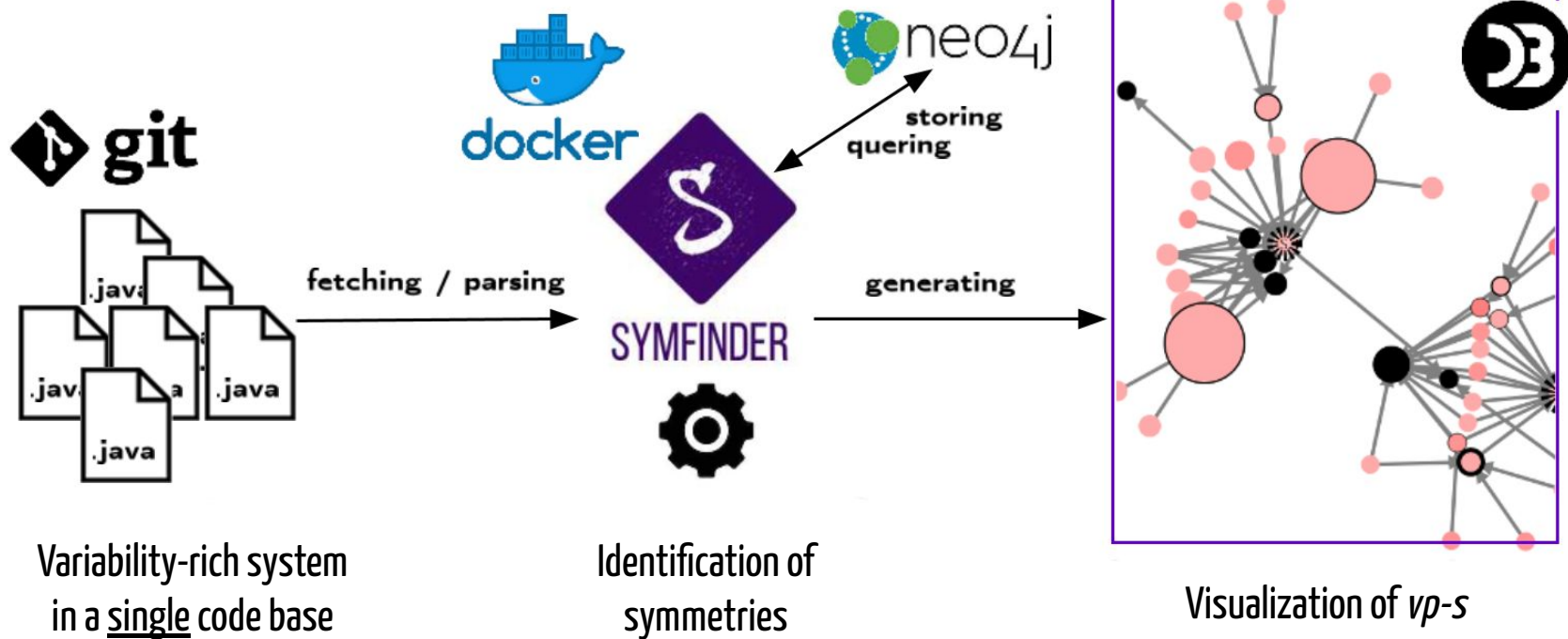
Identifying variation points with variants

Variability implementation technique	↔	local symmetry
- variation point (commonality)	↔	unchanged
- variant (variability)	↔	changes

Identification through local symmetries in core assets

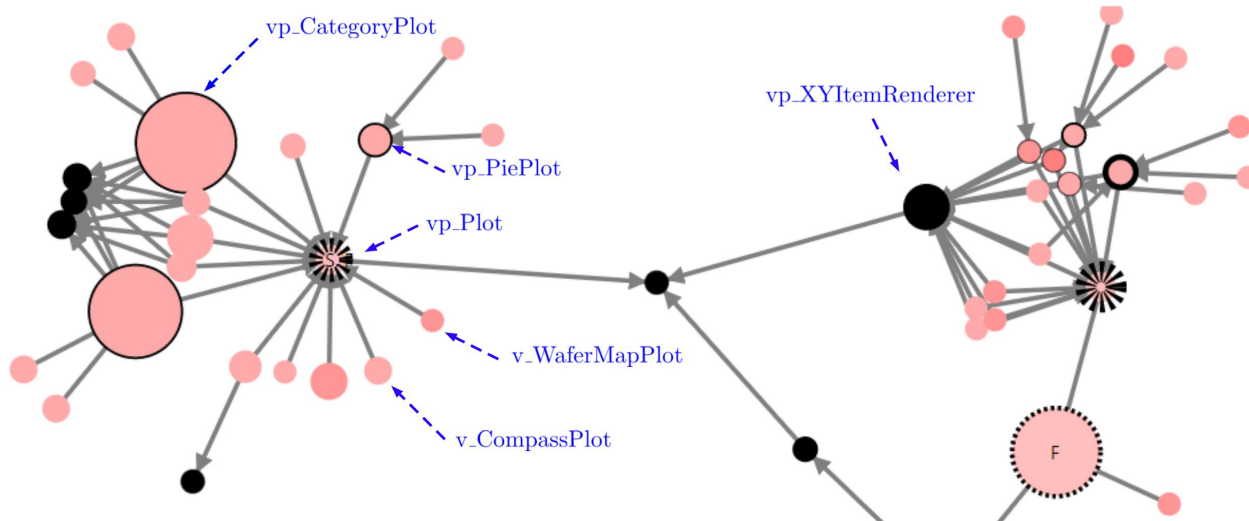
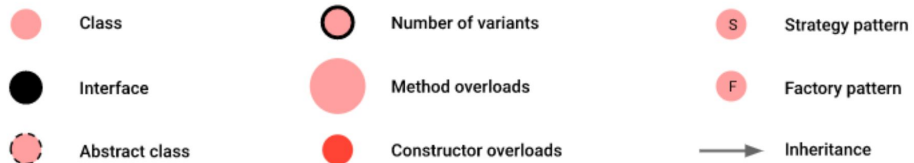
High density of symmetries → variability intense places

symfinder

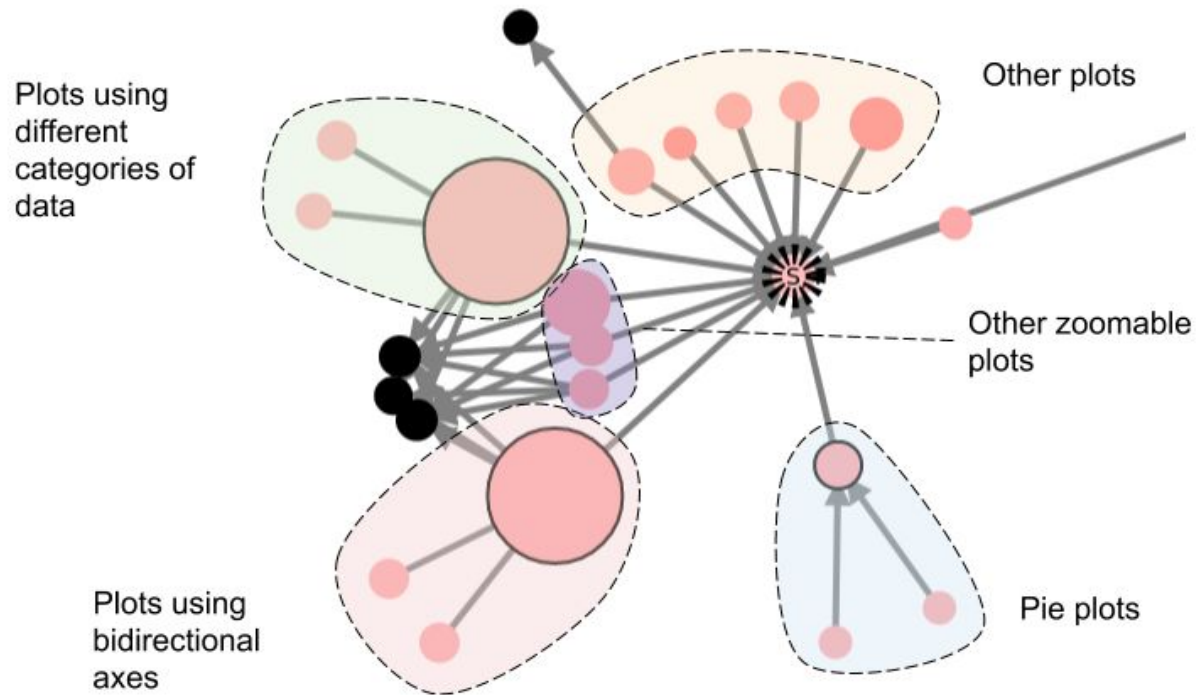


Automatic visualization of *vp*-s with variants

Symfinder Show project information Hide legend jfreechart-v1.5.0 generated by symfinder version 549c

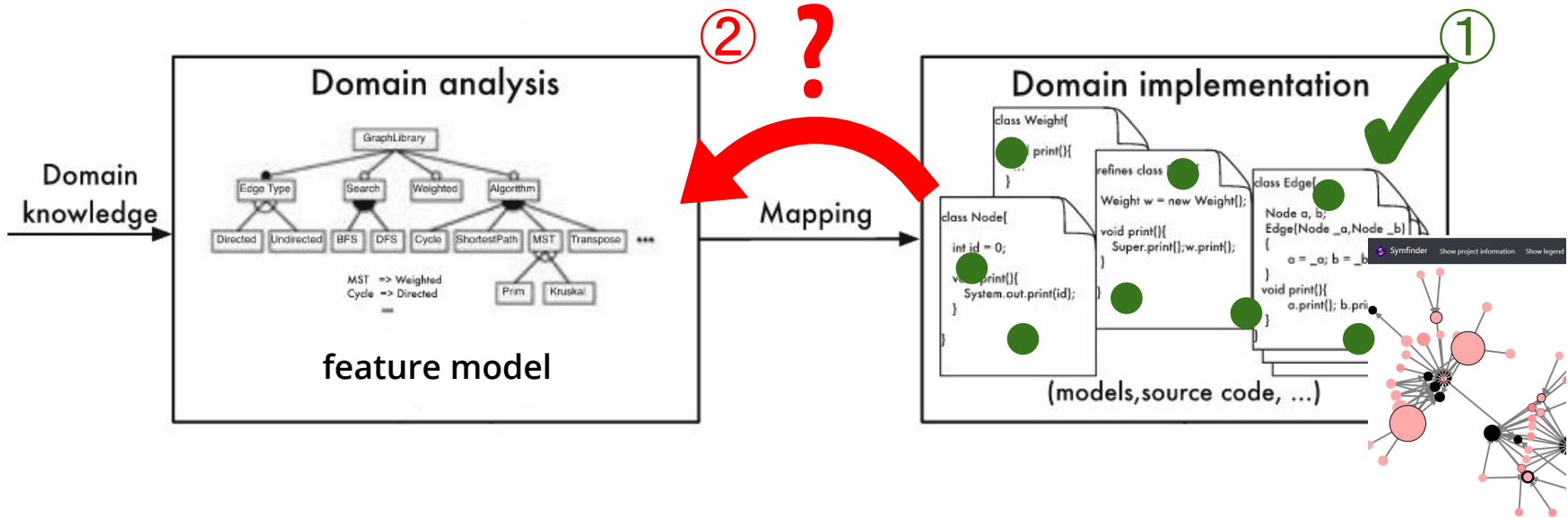


What can be manually found: an example

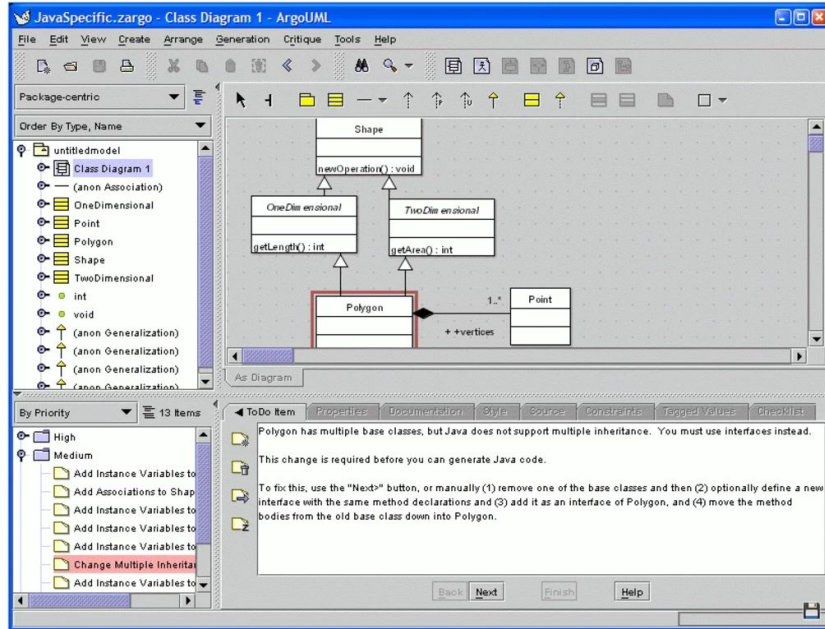


Problem 1: How to identify variability implementations in an existing codebase?

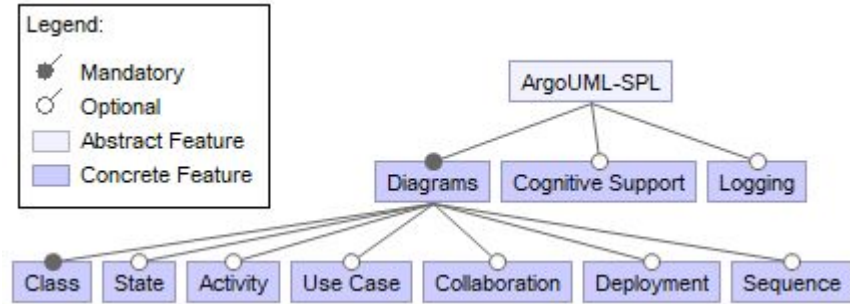
Problem 2: How to map these variability implementations to domain features?



ArgoUML-SPL [Couto2011]

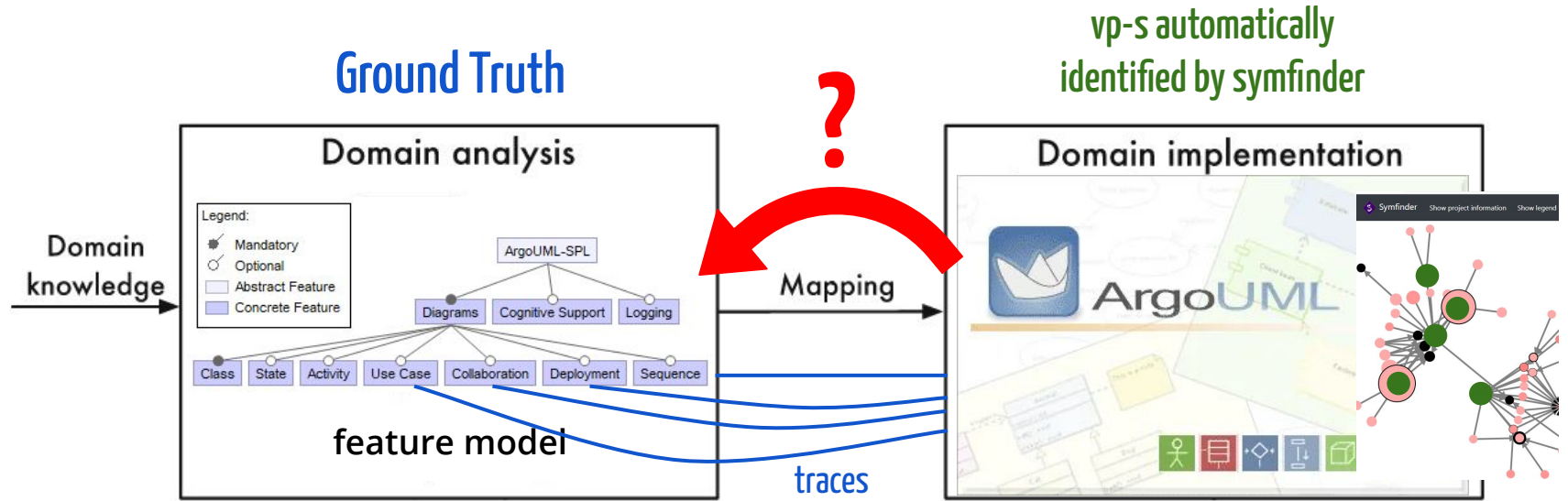


ArgoUML editor



Feature model of ArgoUML-SPL

Question: Are the identified *vp-s* from ArgoUML relevant for a feature mapping?



Experimental setup

Ground Truth

Excerpt of `traces` for USECASE feature

`org.argouml.uml.diagram.use_case.ui.FigActor`

```
///#if defined(USECASEDIAGRAM)  
///@#$LPS-USECASEDIAGRAM:GranularityType:Package  
public class FigActor extends FigNodeModelElement
```

`org.argouml.uml.diagram.use_case.ui.FigClassifierRole`

```
///#if defined(SEQUENCEDIAGRAM)  
///@#$LPS-SEQUENCEDIAGRAM:GranularityType:Package  
public class FigClassifierRole extends FigNodeModelElement
```

-
-
-

Experimental setup

Ground Truth

Excerpt of **traces** for USECASE feature

```
org.argouml.uml.diagram.use_case.ui.FigActor
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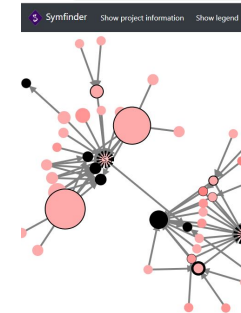
```
org.argouml.uml.diagram.use_case.ui.FigClassifierRole
```

```
///  
//if defined(SEQUENCEDIAGRAM)  
//@#$LPS-SEQUENCEDIAGRAM:GranularityType:Package  
public class FigClassifierRole extends FigNodeModelElement
```

.
. .
. . .

Excerpt of *symfinder* JSON output

```
{  
  "nodes": [  
    {  
      "types": [  
        "CLASS", "METHOD_LEVEL_VP", "VARIANT"  
      ],  
      "constructorVPs": 1,  
      "methodVariants": 0,  
      "classVariants": 0,  
      "methodVPs": 0,  
      "constructorVariants": 3,  
      "name":  
        "org.argouml.uml.diagram.use_case.ui.FigActor"  
    }, ...  
  ],  
  "links": [  
    {  
      "type": "EXTENDS",  
      "source":  
        "org.argouml.uml.diagram.ui.FigNodeModelElement",  
      "target":  
        "org.argouml.uml.diagram.use_case.ui.FigActor"  
    }, ...  
  ]  
}
```



Experimental setup

Ground Truth

Excerpt of `traces` for USECASE feature

```
org.argouml.uml.diagram.use_case.ui.FigActor
```

```
///if defined(USECASEDIAGRAM)  
///@#$LPS-USECASEDIAGRAM:GranularityType:Package  
public class FigActor extends FigNodeModelElement
```

```
org.argouml.uml.diagram.use_case.ui.FigClassifierRole
```

```
///if defined(SEQUENCEDIAGRAM)  
///@#$LPS-SEQUENCEDIAGRAM:GranularityType:Package  
public class FigClassifierRole extends FigNodeModelElement
```

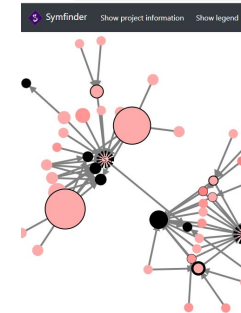
.
. .
.



Manual mapping using
Excel formulae

Excerpt of *symfinder* JSON output

```
{  
  "nodes": [  
    {  
      "types": [  
        "CLASS", "METHOD_LEVEL_VP", "VARIANT"  
      ],  
      "constructorVPs": 1,  
      "methodVariants": 0,  
      "classVariants": 0,  
      "methodVPs": 0,  
      "constructorVariants": 3,  
      "name":  
        "org.argouml.uml.diagram.use_case.ui.FigActor"  
    }, ...  
  ],  
  "links": [  
    {  
      "type": "EXTENDS",  
      "source":  
        "org.argouml.uml.diagram.ui.FigNodeModelElement",  
      "target":  
        "org.argouml.uml.diagram.use_case.ui.FigActor"  
    }, ...  
  ]  
}
```



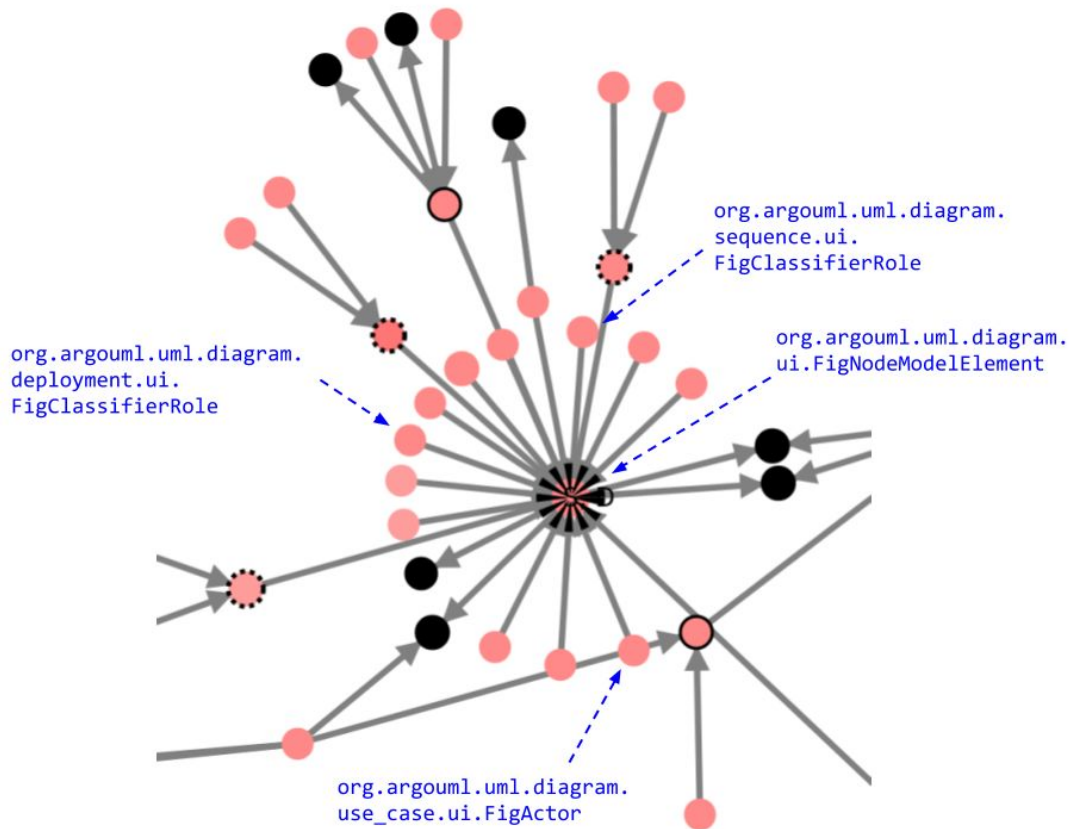
Validation

Feature: Use Case

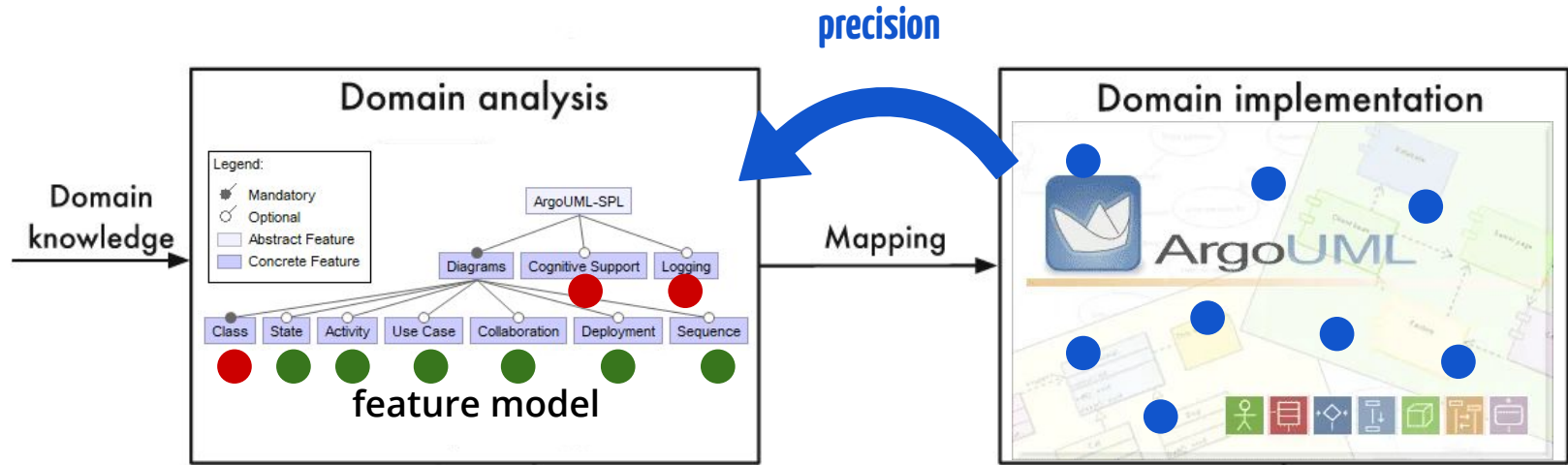
```
//#if defined(USECASEDIAGRAM)  
//@$LPS-USECASEDIAGRAM:GranularityType:Package  
public class FigActor extends FigNodeModelElement
```

Feature: Sequence

```
//#if defined(SEQUENCEDIAGRAM)  
//@$LPS-SEQUENCEDIAGRAM:GranularityType:Package  
public class FigClassifierRole extends FigNodeModelElement
```



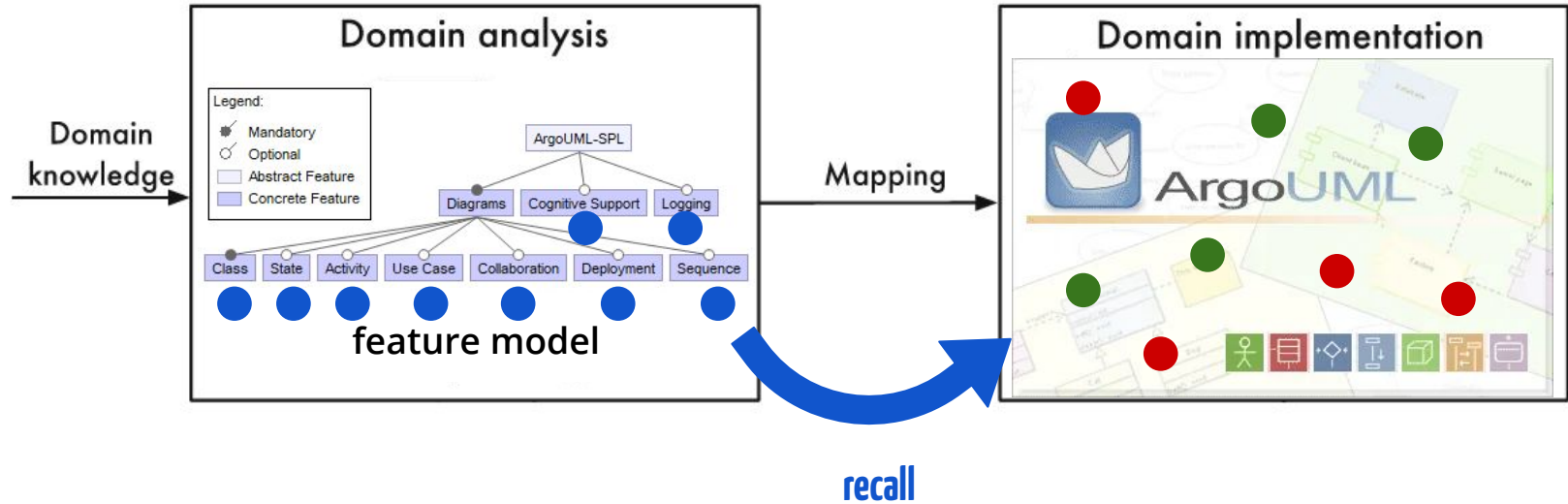
Relevance of the *vp-s*



Precision:

Percentage of identified *vp-s* and variants that could be mapped to domain features

Relevance of the *vp-s*



Recall:

Percentage of features' traces that could be mapped to identified *vp-s* and variants

Relevance of the vp -s

Calculating precision

$$precision = \frac{TP}{TP + FP} = \frac{|T_{gt} \cap I_{vp-v}|}{|I_{vp-v}|} = \frac{593}{1560} = 38\%$$

Low precision was **expected**:

- coarse grain features based on superficial domain knowledge
- not all identified places with a symmetry are related to variability

Relevance of the vp -s

Calculating recall

$$recall = \frac{TP}{TP + FN} = \frac{|T_{gt} \cap I_{vp-v}|}{|T_{gt}|} = \frac{593}{712} = 83\%$$

The missing 17% of traces are **not variability related**:

- initialization classes
- external libraries

Future work

Map the identified *vp*-s with variants to `#ifdef` directives

Take into account *vp*-s with variants at method level

Extend `symfinder` to be able to analyse projects in other languages



Mapping Features to Automatically Identified Object-Oriented Variability Implementations

The case of ArgoUML-SPL

Successful mapping to
preexisting domain features

vp-s detection method is
little precise but **highly
robust** on ArgoUML-SPL

symfinder identifies *vp-s*
with variants relevant for
feature mapping

Availability:

- Public release: tag **vamos2020**
<https://github.com/DeathStar3/symfinder>
- symfinder demonstration
<https://deathstar3.github.io/symfinder-demo/>

Get the paper:



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